

DEED LEARNING RESEARCH SCIENTIST

Amsterdam, The Netherlands

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Education

PhD in Computer Science (Artificial Intelligence)

UvA (University of Amsterdam)

• Title: Deep Future Spatio-temporal Forecasting

• Supervisor: Efstratios Gavves

• Expected graduation: September 2024

Diploma (M.Sc. equivalent) in Electrical and Computer Engineering

AUTH (ARISTOTLE UNIVERSITY OF THESSALONIKI)

- Specialization Field: Electronics and Computer Engineering
- GPA: 7.57/10
- ECTS: 307
- Thesis: Scene Graph Generation using Message Passing Neural Networks and Graph Convolutional Networks
 - · Supervisors: Postdoctoral research associate Christos Diou & Associate Professor Anastasios Delopoulos
 - Visual scene graph generation using an end-to-end neural network that incorporates a message passing neural network, propagating contextual information between objects and their relationships to iteratively refine its predictions, as well as a relationship pruning network that learns to identify and dismiss unlikely relationships.
 - Links to thesis: Greek (Original), English (Translated)

Research Experience _____

Research Assistant

• Amsterdam, The Netherlands

Amsterdam, The Netherlands

Apr. 2020 - June 2024

♀ Thessaloniki, Greece

Oct. 2010 - Nov. 2018

University of Amsterdam

Project: Scene Graph Generation using Graph Transformer Networks

Supervisors: Assistant Professor Efstratios Gavves & Professor Cees G.M. Snoek

• Development of a novel Graph Network for visual scene graph generation that explicitly utilizes both local and global information on the graph space, using Transformer blocks to attend to global context.

· GRAPH PRUNING

KEYWORDS: VISUAL SCENE GRAPH GENERATION • GRAPH NEURAL NETWORKS • TRANSFORMERS

Computer Vision & Machine Learning Engineer

♀ Thessaloniki, Greece

P.A.N.D.O.R.A. ROBOTICS TEAM, ARISTOTLE UNIVERSITY OF THESSALONIKI

Oct. 2014 - Oct. 2015

Mar. 2019 - May 2019

- Development of a general-purpose image classification API using RGB-D sensor data, as well as a benchmarking API for performance evaluation of computer vision algorithms; motion detection and obstacle detection from RGB-D sensor data.
- Honors: 2nd Best Autonomous Robot, Robocup Rescue Competition, Hefei, China, July 2015

KEYWORDS: IMAGE CLASSIFICATION · NEURAL NETWORKS · SVMS · BENCHMARKING · MOTION DETECTION · OBSTACLE DETECTION

Reviewer

I have served as reviewer for the following venues: LoG 2023, NeurIPS 2023, CVPR 2023, ICLR 2023, LoG 2022, CDS 2022, CVIU 2022, PAMI 2022, ICML 2021, ECCV 2020.

Technical Skills _

Programming Languages Python, C++, C, MATLAB/Octave, Java

Deep Learning Frameworks PyTorch, TensorFlow

Deep Learning Libraries PyTorch Geometric, PyTorch Lightning, WandB, Tensorboard, Hydra

Miscellaneous Git, Linux, SLURM, LATEX, TikZ, OpenCV, ROS

Selected Publications

CONFERENCE PAPERS

- Yongtuo Liu, Sara Magliacane, <u>Miltiadis Kofinas</u>, and Efstratios Gavves. **Amortized Equation Discovery in Hybrid Dynamical Systems**. In: *The Forty-first International Conference on Machine Learning (ICML)*. 2024 (ArXiv) (Github)
- Samuele Papa, Riccardo Valperga, David M. Knigge, <u>Miltiadis Kofinas</u>, Phillip Lippe, Jan-jakob Sonke, and Efstratios Gavves. How to
 Train Neural Field Representations: A Comprehensive Study and Benchmark. In: Proceedings of the IEEE/CVF Conference on Computer
 Vision and Pattern Recognition (CVPR). 2024 (ArXiv) (Github)
- <u>Miltiadis Kofinas</u>†, Boris Knyazev, Yan Zhang, Yunlu Chen, Gertjan J. Burghouts, Efstratios Gavves, Cees G.M. Snoek, and David W. Zhang†. **Graph Neural Networks for Learning Equivariant Representations of Neural Networks**. In: *12th International Conference on Learning Representations (ICLR)*. 2024 (ArXiv) (OpenReview) (Github) [Oral] †: Joint first and last authors

- Miltiadis Kofinas, Erik J. Bekkers, Naveen Shankar Nagaraja, and Efstratios Gavves. Latent Field Discovery in Interacting Dynamical Systems with Neural Fields. In: Advances in Neural Information Processing Systems 36 (NeurIPS). 2023 (ArXiv) (OpenReview) (Github)
- Yongtuo Liu, Sara Magliacane, Miltiadis Kofinas, and Efstratios Gavves. Graph Switching Dynamical Systems. In: The Fortieth International Conference on Machine Learning (ICML). 2023 (ArXiv) (Github)
- Miltiadis Kofinas, Naveen Shankar Nagaraja, and Efstratios Gavves. Roto-translated Local Coordinate Frames For Interacting Dynamical Systems. In: Advances in Neural Information Processing Systems 34 (NeurIPS). 2021 (ArXiv) (OpenReview) (Github)

WORKSHOP PAPERS

- Aviv Shamsian†, David W. Zhang†, Aviv Navon, Yan Zhang, Miltiadis Kofinas, Idan Achituve, Riccardo Valperga, Gertjan Burghouts, Efstratios Gavves, Cees Snoek, Ethan Fetaya, Gal Chechik, and Haggai Maron. Data Augmentations in Deep Weight Spaces. In: Workshop on Symmetry and Geometry in Neural Representations (NeurReps), NeurIPS. 2023 (ArXiv) [Oral] †: Equal contribution
- Piyush Bagad†, Floor Eijkelboom†, Mark Fokkema†, Danilo de Goede†, Paul Hilders†, and Miltiadis Kofinas. C-3PO: Towards Rotation Equivariant Feature Detection and Description. In: 3rd Visual Inductive Priors for Data-Efficient Deep Learning Workshop. 2022 (OpenReview) [Oral] †: Equal contribution

Teaching Experience

TEACHING ASSISTANT

Machine Learning I University of Amsterdam, MSc Al 2020, 2021 Deep Learning University of Amsterdam, MSc Al Deep Learning II University of Amsterdam, MSc Al

THESIS SUPERVISION

Daniël (Stijn) Hamerslag

DRIVING ON DATA, OBJECT DETECTION IN URBAN DRIVING SCENES

Daniel Perez Jensen

PREDICTING RIVER FLOW IN ATACAMA REGION WATERSHEDS

Victor Kyriakou

EQUIVARIANT TRAJECTORY FORECASTING WITH LATENT ORIENTATION GRAPH NETWORKS

University of Amsterdam, BSc Al Oct. 2020 - Jan. 2021

University of Amsterdam, MSc Al

Nov. 2021 - July 2022

University of Amsterdam, MSc Al

Nov. 2022 - July 2023

Talks

Learning on Graphs Conference Amsterdam Meetup

NEURAL NETWORKS ARE GRAPHS! GRAPH NEURAL NETWORKS FOR EQUIVARIANT PROCESSING OF NEURAL NETWORKS

Geometric Deep Learning Study Visit

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS

Amsterdam Applied ML Meetup

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS

LoGaG: Learning on Graphs and Geometry Reading Group

ROTO-TRANSLATED LOCAL COORDINATE FRAMES FOR INTERACTING DYNAMICAL SYSTEMS

- Recording (YouTube)

♀ Elsevier, Amsterdam 29 November, 2023

♥ Vrije Universiteit, Amsterdam

♥ Hyperion Lab, Amsterdam

6 Apr. 2022

Virtual

1 Feb, 2022

Languages ___

Greek Native Language

English Certificate of Proficiency in English, University of Michigan

French Diplôme d'études en langue française B2, Centre international d'études pédagogiques (CIEP)

Level C2

Level B2

Academic References ___

Available upon request.